**TDA8941P**1.5 W mono Bridge Tied Load (BTL) audio amplifierRev. 02 - 7 April 2000Product specification

### 1. General description

The TDA8941P is a single-channel audio power amplifier with an output power of 1.5 W at an 16  $\Omega$  load and a 9 V supply. The circuit contains a Bridge Tied Load (BTL) amplifier with an all-NPN output stage and standby/mute logic. The TDA8941P comes in a 8-pin dual in-line (DIP8) package. The TDA8941P is printed-circuit board (PCB) compatible with all other types in the TDA894x family. One PCB footprint accommodates both the mono and the stereo products.

### 2. Features

- Few external components
- Fixed gain
- Standby and mute mode
- No on/off switching plops
- Low standby current
- High supply voltage ripple rejection
- Outputs short-circuit protected to ground, supply and across the load
- Thermally protected
- Printed-circuit board compatible.

### 3. Applications

- Mains fed applications (e.g. TV sound)
- PC audio
- Portable audio.

### 4. Quick reference data

| Table 1:         | Quick reference data     |                                    |     |     |     |      |
|------------------|--------------------------|------------------------------------|-----|-----|-----|------|
| Symbol           | Parameter                | Conditions                         | Min | Тур | Max | Unit |
| V <sub>CC</sub>  | supply voltage           |                                    | 6   | 9   | 18  | V    |
| lq               | quiescent supply current | $V_{CC}$ = 9 V; $R_{L}$ = $\infty$ | -   | 14  | 20  | mA   |
| I <sub>stb</sub> | standby supply current   |                                    | -   | -   | 10  | μA   |





| 1.5 V | / mono | BTL | audio | amplifier |
|-------|--------|-----|-------|-----------|
|-------|--------|-----|-------|-----------|

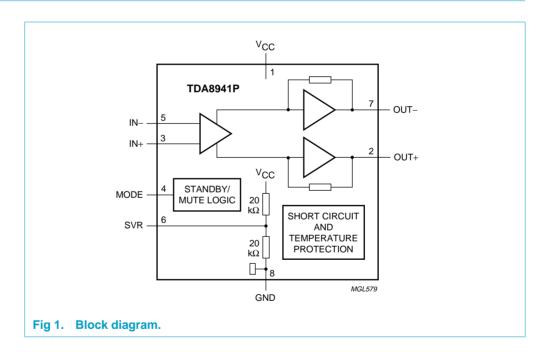
| Table 1: | Quick reference datacontinued   |  |     |      |     |      |
|----------|---------------------------------|--|-----|------|-----|------|
| Symbol   | Parameter                       | Conditions   | Min | Тур  | Max | Unit |
| Po       | output power                    | $\label{eq:thdef} \begin{array}{l} THD = 10\%; R_L = 16 \; \Omega; \\ V_CC = 9 \; V \end{array}$ | 1.2 | 1.5  | -   | W    |
| THD      | total harmonic distortion       | $P_{0} = 0.5 W$  | -   | 0.03 | 0.3 | %    |
| Gv       | voltage gain                    |  | 31  | 32   | 33  | dB   |
| SVRR     | supply voltage ripple rejection |  | 50  | 65   | -   | dB   |

#### . . . . 1.4. . . .

#### **Ordering information** 5.

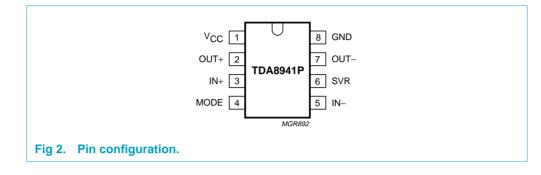
| Table 2: Ordering information |         |   |         |  |  |  |
|-------------------------------|---------|---|---------|--|--|--|
| Type number                   | Package |   |         |  |  |  |
|                               | Name    | Description                                     | Version |  |  |  |
| TDA8941P                      | DIP8    | plastic dual in-line package; 8 leads (300 mil) | SOT97-1 |  |  |  |

#### 6. **Block diagram**



### 7. Pinning information

#### 7.1 Pinning



### 7.2 Pin description

| Table 3:        | Pin description |   |
|-----------------|-----------------|---|
| Symbol          | Pin             | Description                                       |
| V <sub>CC</sub> | 1               | supply voltage                                    |
| OUT+            | 2               | positive loudspeaker terminal                     |
| IN+             | 3               | positive input                                    |
| MODE            | 4               | mode selection input (standby, mute, operating)   |
| IN–             | 5               | negative input                                    |
| SVR             | 6               | half supply voltage decoupling (ripple rejection) |
| OUT-            | 7               | negative loudspeaker terminal                     |
| GND             | 8               | ground  |
|                 |                 |   |

### 8. Functional description

The TDA8941P is a mono BTL audio power amplifier capable of delivering 1.5 W output power to an 16  $\Omega$  load at THD = 10%, using a 9 V power supply. The voltage gain is fixed at 32 dB.

With the three-level MODE input the device can be switched from 'standby' to 'mute' and to 'operating' mode.

The TDA8941P outputs are protected by an internal thermal shutdown protection mechanism and a short-circuit protection.

### 8.1 Input configuration

The TDA8941P inputs can be driven symmetrical (floating) as well as asymmetrical. In the asymmetrical mode one input pin is connected via a capacitor to the signal ground which should be as close as possible to the SVR (electrolytic) capacitor ground. Note that the DC level of the input pins is half of the supply voltage  $V_{CC}$ , so coupling capacitors for both pins are necessary.

The input cut-off frequency is:

$$f_{i(cut-off)} = \frac{1}{2\pi(R_i \times C_i)}$$
(1)

For  $R_i = 45 \text{ k}\Omega$  and  $C_i = 220 \text{ nF}$ :

$$f_{i(cut-off)} = \frac{1}{2\pi (45 \times 10^3 \times 220 \times 10^{-9})} = 16 \,\mathrm{Hz}$$
(2)

As shown in Equation 1 and 2, large capacitor values for the inputs are not necessary; so the switch-on delay during charging of the input capacitors, can be minimized. This results in a good low frequency response and good switch-on behaviour.

**Remark:** To prevent HF oscillations do not leave the inputs open, connect a capacitor of at least 1.5 nF across the input pins close to the device.

### 8.2 Power amplifier

The power amplifier is a Bridge Tied Load (BTL) amplifier with an all-NPN output stage, capable of delivering a peak output current of 2 A.

The BTL principle offers the following advantages:

- · Lower peak value of the supply current
- The ripple frequency on the supply voltage is twice the signal frequency
- No expensive DC-blocking capacitor
- Good low frequency performance.

#### 8.2.1 Output power measurement

The output power as a function of the supply voltage is measured on the output pins at THD = 10%; see Figure 8. The maximum output power is limited by the maximum power dissipation in the plastic package.

#### 8.2.2 Headroom

Typical CD music requires at least 12 dB (factor 15.85) dynamic headroom – compared to the average power output – for transferring the loudest parts without distortion. At  $V_{CC}$  = 9 V,  $R_L$  = 16  $\Omega$  and  $P_o$  = 1 W at THD = 1% (see Figure 6), the Average Listening Level (ALL) – music power – without any distortion yields:

 $P_{o(ALL)} = 1 \text{ W}/15.85 = 63 \text{ mW}.$ 

The power dissipation can be derived from Figure 11 on page 10 for 0 dB respectively 12 dB headroom.

| Table 4. Power fating as function of headroom |                              |                       |  |  |  |
|---|------------------------------|-----------------------|--|--|--|
| Headroom                                      | Power output (THD = 1%)      | Power dissipation (P) |  |  |  |
| 0 dB  | $P_o = 1 W$                  | 1.15 W                |  |  |  |
| 12 dB   | $P_{o(ALL)} = 63 \text{ mW}$ | 0.6 W                 |  |  |  |

For the average listening level a power dissipation of 0.6 W can be used for calculation of the maximum ambient temperature.

### 8.3 Mode selection

The TDA8941P has three functional modes, which can be selected by applying the proper DC voltage to pin MODE. See Figure 4 and 5 for the respective DC levels, which depend on the supply voltage level. The MODE pin can be driven by a 3-state logic output stage: e.g. a microcontroller with additional components for DC-level shifting.

**Standby** — In this mode the current consumption is very low and the outputs are floating. The device is in standby mode when ( $V_{CC} - 0.5 V$ ) <  $V_{MODE}$  <  $V_{CC}$ , or when the MODE pin is left floating (high impedance). The power consumption of the TDA8941P will be reduced to <0.18 mW.

**Mute** — In this mode the amplifier is DC-biased but not operational (no audio output); the DC level of the input and output pins remain on half the supply voltage. This allows the input coupling and Supply Voltage Ripple Rejection (SVRR) capacitors to be charged to avoid pop-noise. The device is in mute mode when  $3 \text{ V} < \text{V}_{\text{MODE}} < (\text{V}_{\text{CC}} - 1.5 \text{ V}).$ 

**Operating** — In this mode the amplifier is operating normally. The operating mode is activated at  $V_{MODE} < 0.5$  V.

#### 8.3.1 Switch-on and switch-off

To avoid audible plops during supply voltage switch-on or switch-off, the device is set to standby mode before the supply voltage is applied (switch-on) or removed (switch-off).

The switch-on and switch-off time can be influenced by an RC-circuit on the MODE pin. Rapid on/off switching of the device or the MODE pin may cause 'click- and pop-noise'. This can be prevented by proper timing of the RC-circuit on the MODE pin.

### 8.4 Supply Voltage Ripple Rejection (SVRR)

The SVRR is measured with an electrolytic capacitor of 10  $\mu$ F on pin SVR at a bandwidth of 10 Hz to 80 kHz. Figure 12 on page 11 illustrates the SVRR as function of the frequency. A larger capacitor value on the SVR pin improves the ripple rejection behaviour at the lower frequencies.

### 8.5 Built-in protection circuits

The TDA8941P contains two types of protection circuits, i.e. short-circuit and thermal shutdown.

#### 8.5.1 Short-circuit protection

**Short-circuit to ground or supply line** — This is detected by a so-called 'missing current' detection circuit which measures the current in the positive supply line and the current in the ground line. A difference between both currents larger than 0.4 A, switches the power stage to standby mode (high impedance).

**Short-circuit across the load** — This is detected by an absolute-current measurement. An absolute-current larger than 2 A, switches the power stage to standby mode (high impedance).

#### 8.5.2 Thermal shutdown protection

The junction temperature is measured by a temperature sensor; at a junction temperature of approximately 150 °C this detection circuit switches the power stage to standby mode (high impedance).

### 9. Limiting values

| In accordance with the Absolute Maximum Rating System (IEC 60134). |  |               |      |                       |      |
|--|--|---------------|------|-----------------------|------|
| Symbol   | Parameter  | Conditions    | Min  | Max                   | Unit |
| V <sub>CC</sub>  | supply voltage                                       | no signal     | -0.3 | +25                   | V    |
|  |  | operating     | -0.3 | +18                   | V    |
| VI   | input voltage  |               | -0.3 | V <sub>CC</sub> + 0.3 | V    |
| I <sub>ORM</sub>   | repetitive peak output current                       |               | -    | 2                     | А    |
| T <sub>stg</sub>   | storage temperature                                  | non-operating | -55  | +150                  | °C   |
| T <sub>amb</sub>   | operating ambient temperature                        |               | -40  | +85                   | °C   |
| P <sub>tot</sub>   | total power dissipation                              |               | -    | 1.25                  | W    |
| V <sub>CC(sc)</sub>  | supply voltage to guarantee short-circuit protection |               | -    | 12                    | V    |

#### Table 5: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

### **10. Thermal characteristics**

| Table 6:             | Thermal characteristics                     |             |            |
|----------------------|---|-------------|------------|
| Symbol               | Parameter                                   | Conditions  | Value Unit |
| R <sub>th(j-a)</sub> | thermal resistance from junction to ambient | in free air | 100 K/W    |

## **11. Static characteristics**

#### Table 7: Static characteristics

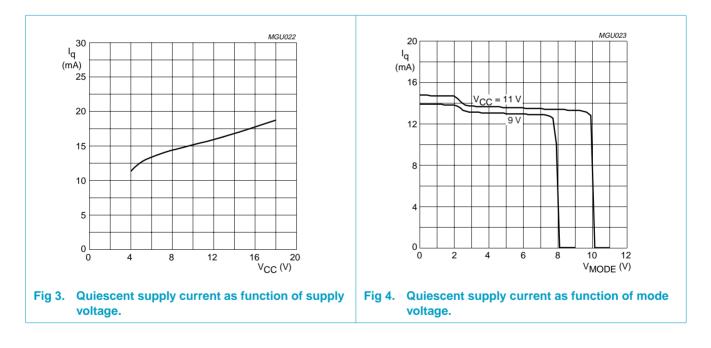
 $V_{CC} = 9 V$ ;  $T_{amb} = 25 \circ C$ ;  $R_L = 16 \Omega$ ;  $V_{MODE} = 0 V$ ;  $V_i = 0 V$ ; measured in test circuit Figure 13; unless otherwise specified.

|                                  |                                    |                         | •            |      |                       |      |
|----------------------------------|------------------------------------|-------------------------|--------------|------|-----------------------|------|
| Symbol                           | Parameter                          | Conditions              | Min          | Тур  | Max                   | Unit |
| V <sub>CC</sub>                  | supply voltage                     | operating               | 6            | 9    | 18                    | V    |
| lq                               | quiescent supply current           | R <sub>L</sub> = ∞      | [1]          | 14   | 20                    | mA   |
| I <sub>stb</sub>                 | standby supply current             | $V_{MODE} = V_{CC}$     | -            | -    | 10                    | μA   |
| Vo                               | DC output voltage                  |                         | [2]          | 4.5  | -                     | V    |
| ΔV <sub>OUT</sub> <sup>[3]</sup> | differential output voltage offset |                         | -            | -    | 200                   | mV   |
| V <sub>MODE</sub>                | mode selection input voltage       | operating mode          | 0            | -    | 0.5                   | V    |
|                                  |                                    | mute mode               | 3            | -    | V <sub>CC</sub> – 1.5 | V    |
|                                  |                                    | standby mode            | $V_{CC} - 0$ | .5 - | V <sub>CC</sub>       | V    |
| I <sub>MODE</sub>                | mode selection input current       | $0 < V_{MODE} < V_{CC}$ | -            | -    | 20                    | μΑ   |
|                                  |                                    |                         |              |      |                       |      |

[1] With a load connected at the outputs the quiescent current will increase, the maximum of this increase being equal to the differential output voltage offset ( $\Delta V_{OUT}$ ) divided by the load resistance (R<sub>L</sub>).

[2] The DC output voltage with respect to ground is approximately  $0.5V_{CC}$ .

 $[3] \quad \Delta V_{OUT} = |V_{OUT+} - V_{OUT-}|.$ 



## **12. Dynamic characteristics**

#### Table 8: Dynamic characteristics

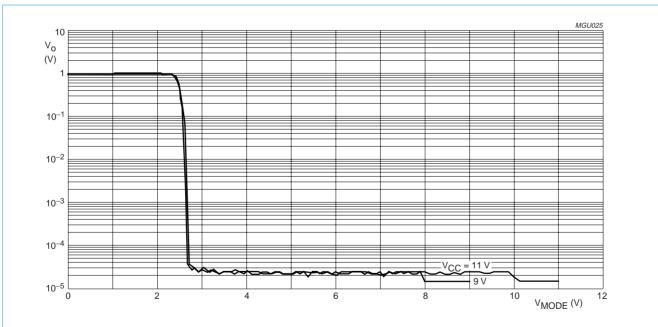
 $V_{CC} = 9 V$ ;  $T_{amb} = 25 \circ C$ ;  $R_L = 16 \Omega$ ; f = 1 kHz;  $V_{MODE} = 0 V$ ; measured in test circuit Figure 13; unless otherwise specified.

|                      |                                 |   |                   |      |     | -    |
|----------------------|---------------------------------|---|-------------------|------|-----|------|
| Symbol               | Parameter                       | Conditions                                | Min               | Тур  | Max | Unit |
| Po                   | output power                    | THD = 10%                                 | 1.2               | 1.5  | -   | W    |
|                      |                                 | THD = 0.5%                                | 0.8               | 1    | -   | W    |
| THD                  | total harmonic distortion       | $P_{o} = 0.5 W$                           | -                 | 0.03 | 0.3 | %    |
| G <sub>v</sub>       | voltage gain                    |   | 31                | 32   | 33  | dB   |
| Z <sub>i(dif)</sub>  | differential input impedance    |   | 70                | 90   | 110 | kΩ   |
| V <sub>n(o)</sub>    | noise output voltage            |   | [1] _             | 90   | 120 | μV   |
| SVRR                 | supply voltage ripple rejection | f <sub>ripple</sub> = 1 kHz               | <sup>[2]</sup> 50 | 65   | -   | dB   |
|                      |                                 | f <sub>ripple</sub> = 100 Hz<br>to 20 kHz | [2] _             | 60   | -   | dB   |
| V <sub>o(mute)</sub> | output voltage                  | mute mode                                 | [3] _             | -    | 50  | μV   |
|                      |                                 |   |                   |      |     |      |

[1] The noise output voltage is measured at the output in a frequency range from 20 Hz to 20 kHz (unweighted), with a source impedance  $R_S = 0 \Omega$  at the input.

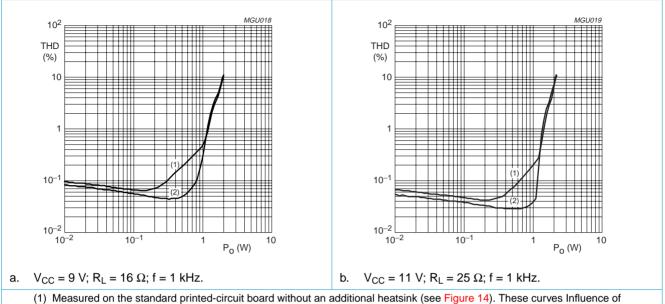
[2] Supply voltage ripple rejection is measured at the output, with a source impedance  $R_S = 0 \Omega$  at the input. The ripple voltage is a sine wave with a frequency  $f_{ripple}$  and an amplitude of 700 mV (RMS), which is applied to the positive supply rail.

[3] Output voltage in mute mode is measured with an input voltage of 1 V (RMS) in a bandwidth of 20 kHz, so including noise.



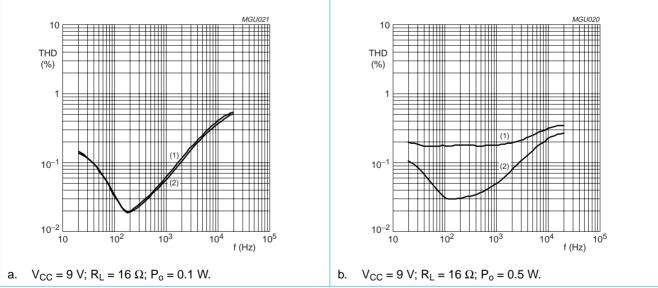


**TDA8941P** 



- Measured on the standard printed-circuit board without an additional heatsink (see Figure 14). These curves Influence o thermal feedback caused by the high power dissipation in combination with the high thermal resistance of the plastic package.
- (2) Measured with a small heatsink on top of the plastic package body;  $R_{th(h-a)} = 30$  K/W.

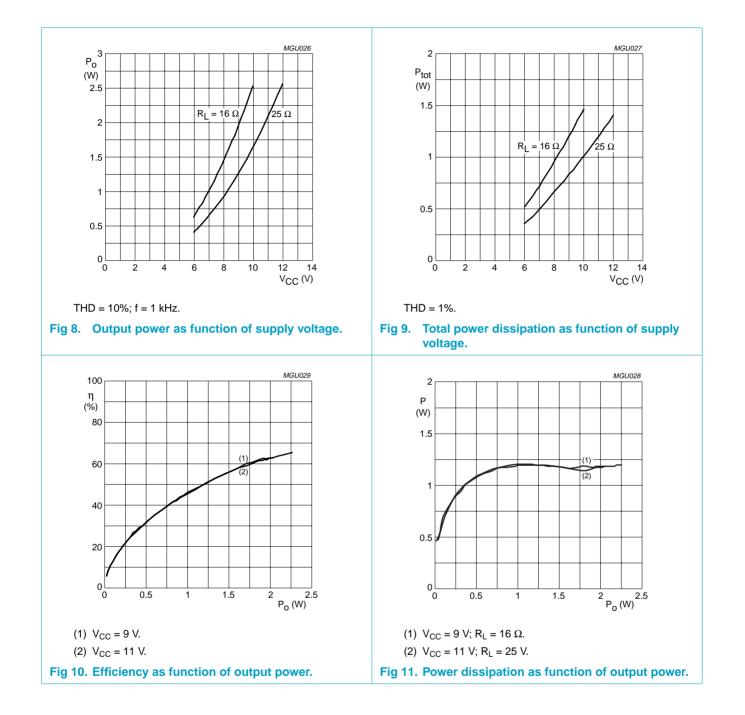
Fig 6. Total harmonic distortion as function of output power.



No bandpass filter applied.

- (1) Measured on the standard printed-circuit board without an additional heatsink (see Figure 14). These curves Influence of thermal feedback caused by the high power dissipation in combination with the high thermal resistance of the plastic package.
- (2) Measured with a small heatsink on top of the plastic package body;  $R_{th(h-a)} = 30$  K/W.
- Fig 7. Total harmonic distortion as function of frequency.

**TDA8941P** 



**TDA8941P** 

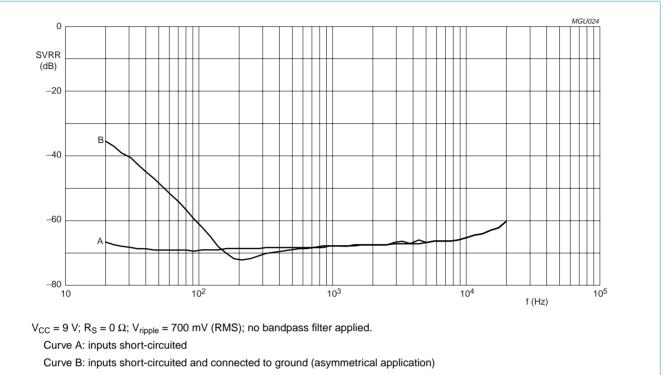
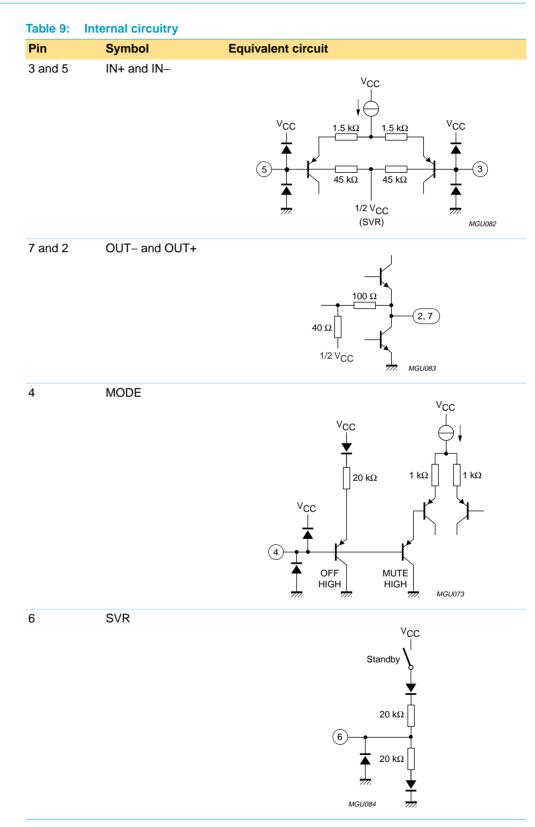


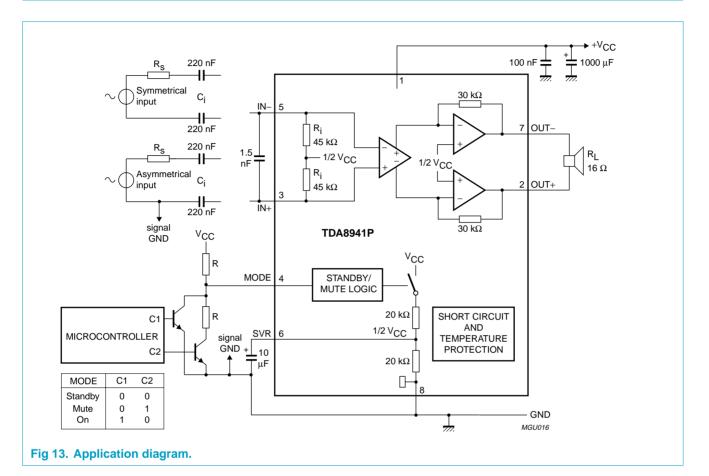
Fig 12. Supply voltage ripple rejection as function of frequency.

# 13. Internal circuitry



**TDA8941P** 

## **14. Application information**



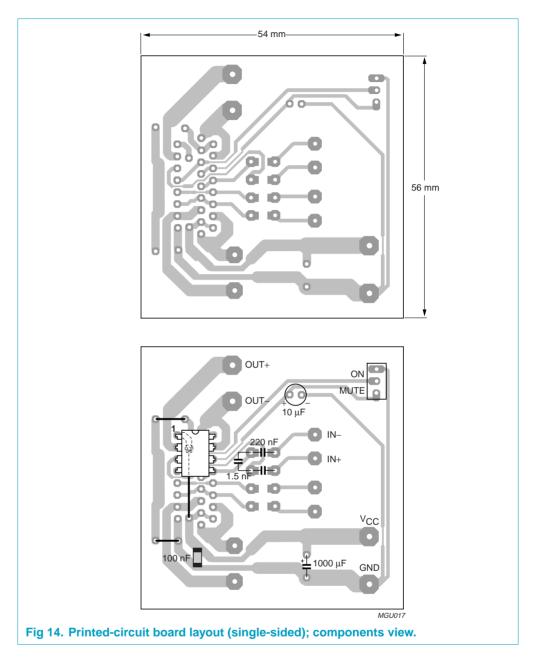
### 14.1 Printed-circuit board (PCB)

#### 14.1.1 Layout and grounding

For a high system performance level certain grounding techniques are essential. The input reference grounds have to be tied with their respective source grounds and must have separate tracks from the power ground tracks; this will prevent the large (output) signal currents from interfering with the small AC input signals. The small-signal ground tracks should be physically located as far as possible from the power ground tracks. Supply and output tracks should be as wide as possible for delivering maximum output power.

# **TDA8941P**

1.5 W mono BTL audio amplifier



#### 14.1.2 Power supply decoupling

Proper supply bypassing is critical for low-noise performance and high supply voltage ripple rejection. The respective capacitor locations should be as close as possible to the device and grounded to the power ground. Proper power supply decoupling also prevents oscillations.

For suppressing higher frequency transients (spikes) on the supply line a capacitor with low ESR – typical 100 nF – has to be placed as close as possible to the device. For suppressing lower frequency noise and ripple signals, a large electrolytic capacitor – e.g. 1000  $\mu$ F or greater – must be placed close to the device.

The bypass capacitor on the SVR pin reduces the noise and ripple on the midrail voltage. For good THD and noise performance a low ESR capacitor is recommended.

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### 14.2 Thermal behaviour and T<sub>amb(max)</sub> calculation

The measured maximum thermal resistance of the IC package,  $R_{th(j-a)}$  is 100 K/W. A calculation for the maximum ambient temperature can be made, with the following parameters:

 $V_{CC}$  = 9 V and  $R_L$  = 16  $\Omega$ 

T<sub>i(max)</sub> = 150 °C.

 $R_{th(tot)}$  is the total thermal resistance between the junction and the ambient.

At  $V_{CC}$  = 9 V and  $R_L$  = 16  $\Omega$  the measured worst-case sine-wave dissipation is 1.15 W; see Figure 11. For  $T_{i(max)}$  = 150 °C the maximum ambient temperature is:

 $T_{amb(max)} = 150 - 1.15 \times 100 = 35 \ ^{\circ}C$ 

The calculation above is for an application at worst-case (stereo) sine-wave output signals. In practice music signals will be applied, which decreases the maximum power dissipation to approximately half of the sine-wave power dissipation (see Section 8.2.2). For  $T_{i(max)} = 150$  °C the maximum ambient temperature is:

 $T_{amb(max)} = 150 - 0.6 \times 100 = 90 \ ^{\circ}C$ 

To increase the lifetime of the IC,  $T_{i(max)}$  should be reduced to 125 °C. This results in:

 $T_{amb(max)} = 125 - 0.6 \times 100 = 65 \ ^{\circ}C$ 

### **15. Test information**

#### **15.1 Quality information**

The General Quality Specification for Integrated Circuits, SNW-FQ-611D is applicable.

#### **15.2 Test conditions**

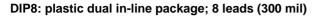
 $T_{amb}$  = 25 °C;  $V_{CC}$  = 9 V; f = 1 kHz;  $R_L$  = 16  $\Omega$ ; audio pass band 22 Hz to 22 kHz; unless otherwise specified.

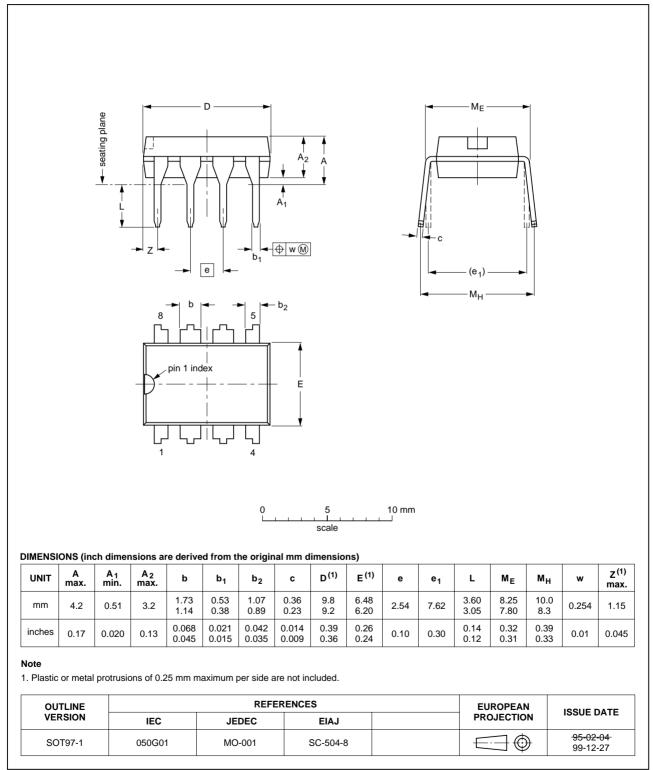
**Remark:** In the graphs as function of frequency no bandpass filter was applied; see Figure 7 and 12.

**TDA8941P** 

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### 16. Package outline





#### Fig 15. DIP8 package outline.

### **17. Soldering**

#### **17.1** Introduction to soldering through-hole mount packages

This text gives a brief insight to wave, dip and manual soldering. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

Wave soldering is the preferred method for mounting of through-hole mount IC packages on a printed-circuit board.

### 17.2 Soldering by dipping or by solder wave

The maximum permissible temperature of the solder is 260 °C; solder at this temperature must not be in contact with the joints for more than 5 seconds. The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature ( $T_{stg(max)}$ ). If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

#### 17.3 Manual soldering

Apply the soldering iron (24 V or less) to the lead(s) of the package, either below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 and 400 °C, contact may be up to 5 seconds.

### 17.4 Package related soldering information

 Table 10:
 Suitability of through-hole mount IC packages for dipping and wave soldering methods

| Package                   | Soldering method |                         |  |
|---------------------------|------------------|-------------------------|--|
|                           | Dipping          | Wave                    |  |
| DBS, DIP, HDIP, SDIP, SIL | suitable         | suitable <sup>[1]</sup> |  |

[1] For SDIP packages, the longitudinal axis must be parallel to the transport direction of the printed-circuit board.

# 18. Revision history

| ev | Date     | CPCN | Description  |
|----|----------|------|--|
| 2  | 20000407 | -    | Product specification; second version; supersedes initial version TDA8941P-01 of   |
|    |          |      | 14 April 1999 (9397 750 04876). Modifications:   |
|    |          |      | <ul> <li>Table 1 on page 1:THD: Max value 0.1% changed to → 0.3%;</li> <li>SVRR: Typ value 65 dB → added</li> </ul>  |
|    |          |      | Ordering options removed   |
|    |          |      | <ul> <li>Section 8 "Functional description":</li> </ul>  |
|    |          |      | - Section 8.1 "Input configuration" on page $3 \rightarrow$ added.   |
|    |          |      | <ul> <li>Section 8.2 "Power amplifier" on page 4:, capable of delivering a peak output<br/>current of 1.5 A → changed to 2 A.</li> </ul>   |
|    |          |      | - Section 8.2.1 "Output power measurement" on page 4 $\rightarrow$ added   |
|    |          |      | - Section 8.2.2 "Headroom" on page 4 $\rightarrow$ added   |
|    |          |      | Section 8.3 "Mode selection":  |
|    |          |      | - Standby mode: $V_{MODE} > (V_{CC} - 0.5 \text{ V}) \rightarrow$ changed to $(V_{CC} - 0.5 \text{ V}) < V_{MODE} < V_{CC}$ ; The power consumption of the TDA8941P will be reduced to <0.18 mW $\rightarrow$ added. |
|    |          |      | <ul> <li>Mute mode: the DC level of the input and output pins remain on half the supply<br/>voltage → added;</li> </ul>  |
|    |          |      | – 2.5 V < V <sub>MODE</sub> < (V <sub>CC</sub> – 1.5 V) $\rightarrow$ changed to 3 V < V <sub>MODE</sub> < (V <sub>CC</sub> – 1.5 V)   |
|    |          |      | - Section 8.3.1 "Switch-on and switch-off" on page 5 $\rightarrow$ added.  |
|    |          |      | • Section 8.4 "Supply Voltage Ripple Rejection (SVRR)" on page 5 $\rightarrow$ added   |
|    |          |      | • Section 8.5 "Built-in protection circuits" on page $6 \rightarrow$ added   |
|    |          |      | • Table 5 on page 6:   |
|    |          |      | – P <sub>tot</sub> value added 1.25 W  |
|    |          |      | – V <sub>CC(sc)</sub> value added 12 V   |
|    |          |      | • Table 7 on page 7: $V_{MODE}$ - mute mode - value Min 2.5 $\rightarrow$ changed to 3 V   |
|    |          |      | Table 8 on page 8:   |
|    |          |      | – THD: Max value 0.1% changed to $\rightarrow 0.3\%$   |
|    |          |      | – SVRR; Typ values 65 and 60 dB $ ightarrow$ added   |
|    |          |      | – $R_{source}$ changed to $\rightarrow$ $R_{S}$ in table and associated table notes  |
|    |          |      | – Table note [2]: 100 mV (RMS) changed to $\rightarrow$ 700 mV (RMS)   |
|    |          |      | • Figure 3 to 12: figures added  |
|    |          |      | • Section 13 "Internal circuitry" on page 12: $\rightarrow$ added  |
|    |          |      | Figure 13: figure modified   |
|    |          |      | • Section 14.1 "Printed-circuit board (PCB)" on page 13: $\rightarrow$ added   |
|    |          |      | • Figure 14: figure added  |
|    |          |      | • Section 14.2 "Thermal behaviour and $T_{amb(max)}$ calculation" on page 15: $\rightarrow$ added  |
|    |          |      | • Section 15 "Test information" on page 15: Section $15.1 \rightarrow$ updated   |
|    |          |      | • Section 15.2 "Test conditions" on page 15: $\rightarrow$ added.  |
| 1  | 19990414 | _    | Preliminary specification; initial version.  |

### **19. Data sheet status**

| Datasheet status          | Product status | Definition <sup>[1]</sup>  |
|---------------------------|----------------|--|
| Objective specification   | Development    | This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.  |
| Preliminary specification | Qualification  | This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips<br>Semiconductors reserves the right to make changes at any time without notice in order to improve design and<br>supply the best possible product. |
| Product specification     | Production     | This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.   |

[1] Please consult the most recently issued data sheet before initiating or completing a design.

### **20. Definitions**

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Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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Argentina: see South America Australia: Tel. +61 2 9704 8141, Fax. +61 2 9704 8139 Austria: Tel. +43 160 101, Fax. +43 160 101 1210 Belarus: Tel. +375 17 220 0733, Fax. +375 17 220 0773 Belgium: see The Netherlands Brazil: see South America Bulgaria: Tel. +359 268 9211, Fax. +359 268 9102 Canada: Tel. +1 800 234 7381 China/Hong Kong: Tel. +852 2 319 7888, Fax. +852 2 319 7700 Colombia: see South America Czech Republic: see Austria Denmark: Tel. +45 3 288 2636, Fax. +45 3 157 0044 Finland: Tel. +358 961 5800, Fax. +358 96 158 0920 France: Tel. +33 14 099 6161, Fax. +33 14 099 6427 Germany: Tel. +49 40 23 5360, Fax. +49 402 353 6300 Hungary: see Austria India: Tel. +91 22 493 8541, Fax. +91 22 493 8722 Indonesia: see Singapore Ireland: Tel. +353 17 64 0000, Fax. +353 17 64 0200 Israel: Tel. +972 36 45 0444, Fax. +972 36 49 1007 Italy: Tel. +39 039 203 6838, Fax +39 039 203 6800 Japan: Tel. +81 33 740 5130, Fax. +81 3 3740 5057 Korea: Tel. +82 27 09 1412, Fax. +82 27 09 1415 Malaysia: Tel. +60 37 50 5214, Fax. +60 37 57 4880 Mexico: Tel. +9-5 800 234 7381 Middle East: see Italy

**For all other countries apply to:** Philips Semiconductors, International Marketing & Sales Communications, Building BE, P.O. Box 218, 5600 MD EINDHOVEN, The Netherlands, Fax. +31 40 272 4825 Netherlands: Tel. +31 40 278 2785, Fax. +31 40 278 8399 New Zealand: Tel. +64 98 49 4160, Fax. +64 98 49 7811 Norway: Tel. +47 22 74 8000, Fax. +47 22 74 8341 Philippines: Tel. +63 28 16 6380, Fax. +63 28 17 3474 Poland: Tel. +48 22 5710 000, Fax. +48 22 5710 001 Portugal: see Spain Romania: see Italy Russia: Tel. +7 095 755 6918, Fax. +7 095 755 6919 Singapore: Tel. +65 350 2538, Fax. +65 251 6500 Slovakia: see Austria Slovenia: see Italy South Africa: Tel. +27 11 471 5401, Fax. +27 11 471 5398 South America: Tel. +55 11 821 2333. Fax. +55 11 829 1849 Spain: Tel. +34 33 01 6312, Fax. +34 33 01 4107 Sweden: Tel. +46 86 32 2000, Fax. +46 86 32 2745 Switzerland: Tel. +41 14 88 2686, Fax. +41 14 81 7730 Taiwan: Tel. +886 22 134 2865, Fax. +886 22 134 2874 Thailand: Tel. +66 27 45 4090, Fax. +66 23 98 0793 Turkey: Tel. +90 216 522 1500, Fax. +90 216 522 1813 Ukraine: Tel. +380 44 264 2776, Fax. +380 44 268 0461 United Kingdom: Tel. +44 208 730 5000, Fax. +44 208 754 8421 United States: Tel. +1 800 234 7381 Uruguay: see South America Vietnam: see Singapore Yugoslavia: Tel. +381 11 3341 299, Fax. +381 11 3342 553

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